Structured illumination microscopy combined with machine learning enables the high throughput analysis and classification of virus structure.

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Abstract

Optical super-resolution microscopy techniques enable high molecular specificity with high spatial resolution and constitute a set of powerful tools in the investigation of the structure of supramolecular assemblies such as viruses. Here, we report on a new methodology which combines Structured Illumination Microscopy (SIM) with machine learning algorithms to image and classify the structure of large populations of biopharmaceutical viruses with high resolution. The method offers information on virus morphology that can ultimately be linked with functional performance. We demonstrate the approach on viruses produced for oncolytic virotherapy (Newcastle Disease Virus) and vaccine development (Influenza). This unique tool enables the rapid assessment of the quality of viral production with high throughput obviating the need for traditional batch testing methods which are complex and time consuming. We show that our method also works on non-purified samples from pooled harvest fluids directly from the production line.

Introduction

The potential of super-resolution microscopy (SRM) to unravel details of the structure and replication of viruses was recognised early on in the development of the methodology 1-12. Since then, SRM has been used to provide unprecedented insights into viral protein architecture 3-6. Previous work has focused on those SRM techniques that achieve the highest theoretical resolution, such as Stimulated Emission Depletion (STED) 7 and Single Molecule Localisation Microscopy (SMLM) 8,9. Whilst offering high fidelity data, the downside is the associated long acquisition time required by these methods, limiting their application to the imaging of static samples at low throughput. A much faster technique, although inferior in spatial resolution, is Structured Illumination Microscopy (SIM) 10,11 and this has been applied to study large viruses such as the prototypic poxvirus 5,12. In addition to understanding the structure of viruses, there is also need to identify and analyse classes of structures within large viral populations, especially in the biotechnology industry where virus quality is often compromised by large scale production operations and the virus product is often characterised by significant morphological heterogeneities. In particular, campaigns of influenza immunization rely heavily on the timely and efficient production of specific virus strains. Similarly, a deeper understanding of the structural heterogeneity of oncolytic viruses such as Newcastle Disease Virus (NDV) 13,14 would enable optimization of the production processes and in turn improve the development of virotherapy. However, quantifying and understanding this structural heterogeneity and relating it to virus efficacy requires the imaging of large numbers of viruses at sufficient spatial resolution to reveal characteristic morphological details. Typically, this is achieved by extracting batches from the production process, with elaborate subsequent purification and preparation steps before characterisation by Transmission Electron Microscopy (TEM) 15-17. Although TEM can achieve relatively high imaging throughput if the highest resolution is not necessary, its contrast remains unspecific and therefore typically does not permit discerning the presence of particular proteins in the virus envelope. Also, the typical signal-to-noise ratios achieved by are not sufficient to permit automated, robust and efficient downstream analysis of
structural features at the single particle level. It is therefore challenging for TEM to be of practical use during production operations.

Here, we demonstrate that rapid high resolution imaging with Total Internal Reflection SIM fluorescence microscopy (TIRF-SIM) \(^{18-20}\), combined with a machine learning (ML) approach to analyse and classify structures in virus batches offer a great opportunity to circumvent these problems. We present MiLeSIM (Machine Learning Structured Illumination Microscopy) as an efficient combination of SRM, ML-based classification \(^{21,22}\) and advanced image analysis for the quantification of morphological heterogeneities in large virus populations. We use ML algorithms to perform a classification of super-resolved images of a heterogeneous virus population into particle classes with distinct and characteristic structural features (e.g. spherical, filamentous). The classified subpopulations are then further analysed through image analysis pipelines that are specifically adapted for each structural class. We and others have shown that appropriate model fitting can lead to precision in structural parameters beyond the resolution of the images used \(^{3,23}\).

The method combines speed and specificity and allows an in-depth exploration of large virus populations that is unachievable by electron microscopy (EM). The method has potential in the industrial production of viruses e.g. for oncolytic virotherapy and vaccine development.

First, we compare TIRF-SIM with alternative imaging modalities and show that it is the method of choice to investigate virus structure at high-throughput (~220 virus particles/s, see Supplementary Note 1) with a spatial resolution reaching ~90 nm. The large datasets obtained with TIRF-SIM were then fed into an ML algorithm for the automated classification of Newcastle Disease Virus (NDV) and live attenuated influenza virus (LAIV) vaccines, enabling further shape-specific quantitative analyses for a structural description of viral subpopulations. The purpose of our study is to validate the MiLeSIM approach as a powerful analysis tool for biotechnological processes involving virus production both in industry and in the research laboratory.

Results

**TIRF-SIM offers an optimal combination of throughput and resolution for the imaging of virus structure**

First, we explored and compared three common SRM modalities for the structural investigation of purified NDV virus, namely direct stochastic optical reconstruction microscopy, dSTORM, stimulated emission depletion microscopy, STED and TIRF-SIM. NDV viruses were labelled for the envelope glycoprotein Hemagglutinin-Neuraminidase (HN) and imaged with all three SRM imaging techniques (see Figure 1). Labelling for HN allows us to directly and specifically observe the shape of the virus particles. For comparison, a conventional (non-super-resolved) TIRF wide-field image is also shown. Typical shapes observed with TIRF-SIM are shown in Figure 1(b). TIRF-SIM provides clear structural details to discern filamentous, spherical and rod-like structures in large NDV populations. A comparison of performance parameters (resolution and imaging speed) for the different methods is presented in Figure 1 – Figure supplement 1(a). It is clear that improving resolution beyond the ~90 nm offered by TIRF-SIM (see Figure 1 – Figure supplement 1(b)) comes at a significant cost in acquisition times and throughput. Furthermore, although dSTORM and STED offer theoretically higher resolution than SIM, the images obtained with these methods do not reveal additional structural details that are not also resolved by TIRF-SIM images. This indicates that the ~2-fold resolution improvement provided by TIRF-SIM is sufficient for the structural study presented here.

Traditionally, EM has been the method of choice for observing sub-diffraction structures of virus particles (see Figure 1 – Figure supplement 2 for examples of particles). Here we show that TIRF-SIM can offer significant advantages compared to EM (summarized in Table 1). The improvement in molecular specificity allows an unambiguous identification of viral components; the high signal-to-noise ratio (SNR) furthermore enables a robust and straightforward application of further image analysis steps (identification and
classification of virus particles). Also, the capability of investigating unpurified and aqueous samples makes TIRF-SIM ideally suited to the present application.

Figure 1: Super-resolution microscopy (SRM) for the study of NDV virus structure. (a) Representative images of purified NDV viruses with different imaging modalities. (b) Representative images of a purified NDV virus population imaged with TIRF-SIM and their corresponding TIRF wide-field image. WF: wide-field TIRF microscopy. Scale bar: 1 µm.

Workflow of MiLeSIM

The images obtained with TIRF-SIM show a number of stereotypical virus structures in NDV samples labelled for HN, indicating a large morphological diversity in the virus populations that may stem from variability occurring during viral replication or at the purification stage. Understanding the origins and consequences of such heterogeneity informs not only on the life cycle of the virus but can also provide essential insights into the virus production process to manufacturers of virus-based therapeutics. An automated classification of virus shapes would enable the quantification of virus heterogeneity and permit further analysis of each individual class independently. The workflow to achieve these goals is shown in Figure 2.

Individual virus particles are first identified by automated segmentation and then fed to the ML routine for classification. We used a supervised ML algorithm (here a random forest algorithm) to ensure the robustness of the method and for ease of implementation. We identified 6 major structural classes in the NDV samples which we divide into long and short filamentous, small and large spherical, rod-like and unknown structures. The unknown class is made of clumps of viral material with no consistent and identifiable shapes. A control sample that was prepared identically to the other samples except without virus particles present allowed us to identify that non-specific bindings of antibodies appear as rare, dim and small point-like structures that could easily be discriminated and excluded from further analysis.

The filamentous particles (long and short) class is further analysed by automatic extraction of the linear backbone of structures and measurement of their length. The width of these filamentous structures appeared to be limited by the resolution of the imaging technique (~90 nm for TIRF-SIM, see Figure 1 – Figure supplement 1, but also observed in higher resolution approaches such as dSTORM) and therefore, we considered the filamentous class as 1D structures. The spherical structures were analysed by estimating their equivalent radius from the area of the particle. We note that other methods for estimation of the radius, e.g. the ellipsoid localization microscopy (ELM) analysis, could also be used here. The latter fits a shape model to imaging data to permit the extraction of structural parameters with precision higher than the inherent resolution of the imaging method. A similar model-based fitting approach was used to fit rod-like viral particles and to obtain length and width parameters for this structural class (see materials and methods section and Figure 2 – Figure supplement 1 for details).
Figure 2: Workflow of automated detection, classification and analysis of NDV viral particles. SIM image (a) and segmented particles (b). The classified single-virus images (c) can be further analysed with a set of class-specific tools (d). For the backbone analysis the mask and backbone are showed in blue and white respectively. For the model-fitting approach (spherical and rod-like), the data and model are showed in green and magenta respectively. LF: long filamentous, SF: short filamentous, LS: large spherical, SS: small spherical, RD: rod shape, UK: unknown. $L_F$, $D_{LS}$, $L_{RD}$ and $W_{RD}$ represents the length of the filamentous particles, the diameter of the large spherical, and the length of the rod-shaped particles and the width of the rod-shaped particles respectively. Images of individual particles cover a field of view of 1.6 x 1.6 µm.

Classification of virus structures using supervised machine learning algorithms

The structural classification was performed using a supervised ML algorithm which allows for rapid and automated classification of large datasets. The choice of algorithm and the set of features (often called predictors) extracted for each identified particle were optimised to maximise the overall accuracy of the model based on the training dataset (comprising of 370 manually annotated particles). Here, the model accuracy is defined as the fraction of correctly classified particles across all classes. Figure 3(a) describes the list of chosen individual features (selected from basic shapes features, Hu’s image moments, features obtained from the pre-trained convolutional neural network (CNN) AlexNet 25 and from Speeded Up Robust Features, SURF 27). The predictors were selected based on the following criteria: basic structural features of the particles (e.g. area, eccentricity) and Hu’s moments were chosen because they are rotationally and translationally symmetric. For the features from AlexNet and SURF a feature selection approach was designed based on maximising the standard deviation across the different structural classes. This approach constitutes a more rational choice compared to simple principal component analysis (PCA), which does not typically take the information regarding the classes into account, therefore our method selects for predictors that have high potential for class discrimination. This data reduction narrowed down the number of predictors to 6 for AlexNet and 6 for SURF.
A total of 24 predictors was finally chosen: 7 based on basic shapes (area, ratio of axis lengths, eccentricity, solidity, perimeter-to-area, mean intensity, standard deviation of pixel intensities), 5 of Hu’s image moments (Hu1, Hu4, Hu5, Hu6 and Phi4), 6 features obtained from the pre-trained convolutional neural network (CNN) AlexNet and 6 from a SURF bag of features. The classification workflow is described in Figure 3 – Figure supplement 1.

Panels described in Figure 3(b) show examples of scatter plot from arbitrarily chosen pairs of predictors highlighting that some predictors support classification across specific classes better than other combinations (identifiable clusters of certain classes). Here, the training dataset was used to build a scatter plot of pairs of predictors with the knowledge of their true classification (see colour scheme). For instance, the pair of predictors \( \text{L}_1/\text{L}_2 \) and \( \text{Area} \) show a good separation between long filamentous (dark blue labels) and unknown structures (black labels). The confusion matrix (Figure 3(c)) highlights the effective true positive rate (TPR) and positive predictive values (PPV) across the different classes with a model accuracy of 88.4%. We note that some long filamentous viruses are misclassified as small filamentous, some small filamentous are misclassified as small spherical and that, on occasion, some unknown structures populate the predicted long and large spherical structure classes. Considering the simple shapes of these viruses, it is expected that a small fraction of particles are misclassified as structures with close resemblance.
The scoring of the predictors presented in Figure 3(d) indicates the average accuracy of each individual predictor. A high score indicates a high capacity to discriminate between different classes. The scoring was performed by measuring the accuracy of the classification for many combinations of predictors and distributing the accuracy score across the predictors tested (see Materials and Methods for details). In other words, if a combination of 2 predictors alone give an accuracy of 60%, a score of 30% is awarded to both individual predictors. This method was repeated and scores represent averages across > 13,000 different combinations of predictors.

Structural details of an NDV virus population

We analysed a total of ~6,500 particles using MiLeSIM and established that 49.7% of NDV particles presented a filamentous shape whereas the large spherical, small spherical and rods represent 18.6%, 7.8% and 7.3% of the total population, respectively (Figure 4(a)). In addition to structural classification, the high-resolution images also permitted a dimensional analysis to be performed at the single particle level. We estimated the particle radius from both small and large spherical particles by calculating the equivalent radius from the particle area; backbone extraction to the short and long filamentous particles, to estimate the particle length; and designed a model fitting for the rod structures. Figure 4 shows the distribution of structural parameters for each class. We observe that both long filamentous and large spherical are well described by a Gamma distribution whereas the small filamentous and small spherical are well described by a Gaussian distribution. The model-fitting applied to the rod-shaped particles (see materials and methods and Figure 2 – Figure supplement 1 for details) allows the extraction of both the width and length of each particle. Therefore, it is possible to plot the distribution of structural parameters as a contour plot (Figure 4(c)).

We estimated the mean and standard deviation of the structural parameters from the distributions and obtained: $L_{LF} = 650 \pm 430$ nm, $L_{SF} = 200 \pm 100$ nm, $D_{LS} = 338 \pm 94$ nm, $D_{SS} = 190 \pm 10$ nm. For the rod-shaped particles, we observed that the width $W_{RD} = 135 \pm 30$ nm and the length $L_{RD} = 610 \pm 350$ nm (all rounded to two significant figures, ± represents the standard deviation of the distribution). These values are distributed around two populations as shown on the contour plot in Figure 4(d). However, we note that the radius analysis based on the area of the particle used here constitutes an overestimate of the physical radius of the particle due to the broadening caused by the point-spread function. It is possible to estimate a more accurate diameter of the underlying spherical structures by using the ELM analysis. The results obtained from the ELM analysis of the large spherical structures are shown in Figure 4 – Figure supplement 1(a). The ELM diameter obtained for the large spherical particles (220 nm ± 69 nm) is in good agreement with an area-based diameter of 338 nm and a resolution of 90 nm.

It should be noted that the small spherical distribution is centred on the value of optical resolution of our SIM microscope, which indicates that the small spherical structures the small spherical structures are smaller than the point-spread-function.
Figure 4: Quantitative analysis of NDV. The distribution of structural parameters for all classes was obtained from a total of ~6,500 virus particles. LF: long filamentous, SF: short filamentous, LS: large spherical, SS: small spherical, RD: rod-shape, UK: unknown. Images of individual particles cover a field of view of 1.6 x 1.6 µm.

MiLeS is capable of assaying influenza strains used for vaccine production in purified and non-purified samples from the production line

We applied our approach to four different strains of Live Attenuated Influenza Virus (LAIV) immuno-labelled for the glycoprotein Hemagglutinin (HA) present on the exterior of the viral envelope. The shape of the virus particles obtained here were classified using the same classifier as for NDV. The LAIV virus population was dominated by spherical structures (> 60%). Figure 5 shows the distribution of particle sizes for four virus strains: a B-Victoria subtype (B/Brisbane/60/2008), a B-Yamagata subtype (B/Phuket/3073/2013) and two subtype A H1N1 strains (A/South Dakota /06/07 and A/Bolivia/559/2013). The fractions of small and large spherical particles are shown, as well as the equivalent radii and representative images of the viruses. It is clearly seen that B-Victoria particles consist of mostly large hollow particles with an equivalent radius of ~130 nm, a value that is in good agreement with the ELM analysis and a resolution of 90 nm (Figure 4 – Figure supplement 1(b)).

In contrast, the B-Yamagata strain shows small and large particles of equal amount, indicating that the particles sizes are distributed around the region of overlap between small and large particles. This is confirmed by the nearly identical equivalent radius distributions.
Figure 5: MiLeSIM approach applied to Live Attenuated Influenza Virus (LAIV). 2 types of B and A viruses were analysed here. The population was dominated by small and large spherical particles. The distributions of equivalent radius are shown here for both the large and small spherical for direct comparisons. The number of particles analysed were N=3,821, 4704, 1,062 and 1,756 for B/Brisbane/60/2008 (B-Victoria), B/Phuket/3073/2013 (B-Yamagata), A/South Dakota/06/2007 and A/Bolivia/559/2013 respectively. Images of individual particles cover a field of view of 1.6 x 1.6 µm.

Both A strains appeared clearly dominated by small spherical particles with sizes close to the resolution limit of our imaging. However, our high-throughput approach reveals subtle differences in the distribution of small spherical structures where the A/South Dakota viruses appear more heterogeneous (standard deviation ~10 nm), whereas the A/Bolivia viruses are sharply distributed (standard deviation ~4 nm).

We also investigated the potential of directly imaging pool harvested fluid (PHF). LAIV are commonly propagated in embryonated hens’ eggs where progeny viruses are released into the allantoic fluid of the egg. This fluid is harvested from numerous eggs and pooled. This constitutes a very basic and commonly used virus material. It is easy to produce and does not undergo any downstream purification. Consequently, PHF is impure, containing a variety of egg-derived impurities. The high molecular specificity of fluorescence microscopy allowed us to visualize the structure of the viruses with the same image quality directly in PHF despite the presence of a large amount of impurities (Figure 5 – Figure supplement 1(a)). The structural analysis of the B-Victoria strains from MVB (Figure 5) and PHF (Figure 5 – Figure supplement 1(b)) allows us to decipher the effect of purifications steps on the structural properties of the population. The fraction of unknown structures dropped from 23% to 8% between MVB and PHF respectively. This change in fraction of unknown structure may be a result of the different densities of viruses on the cover slip. We observed a lower density of virus particles in the PHF preparations, which may lead to fewer aggregated classes and therefore fewer unidentifiable structures. In addition, whereas the PHF shows a nearly equal amount of small and large spherical structures, the MVB preparation is missing a large population of small spherical compared to the PHF. This is also reflected by the larger average diameters observed in the MVB compared to the PHF ($D_{SS} = 191 \pm 12$ nm and $198 \pm 14$ nm and $D_{LS} = 241 \pm 56$ nm and $275 \pm 49$ nm for PHF and MVB respectively).
MiLeSIM therefore enables the study of unpurified samples and allows probing the virus production at any intermediate levels of production and purification. This constitutes a strong advantage over electron microscopy (EM) techniques which require the use of highly purified samples and elaborate preparation protocols.

**Discussion**

We have demonstrated the potential of high-throughput imaging of virus structures, taking advantage of the optimal combination of speed and resolution afforded by the TIRF-SIM imaging method. TIRF-SIM provided sufficient resolution to identify, discriminate and analyse individual viral structural classes with high specificity, even in non-purified samples. Our approach combines machine learning to classify NDV viruses, followed by a model-based or direct quantification of virus structural parameters. The method yielded similar results both in purified samples and in samples from unfiltered PHF offering promise for use as an assay during virus production. We were able to image up to ~220 particles / second at 90 nm resolution, vastly increasing imaging throughput compared to alternative super-resolution methods, improving sensitivity and specificity in comparison to TEM. Furthermore EM does not feature the specificity to analyse virus samples in their aqueous, unaltered unpurified forms. We were able to observe large structural variabilities in the NDV population and also between different strains of LAIV.

Our particular classification uses random forest with a selection of predictors from simple shape parameters, rotational and translational invariant image moments and features from AlexNet and common feature for image recognition such as SURF. The model accuracy is ~88.4% and the mis-classification occur between classes that are similar (between small spherical and small filamentous for instance). The structural parameters that we extract from the model fitting are precise beyond the image resolution as they take into account the finite optical resolution. This therefore reveals subtle differences in populations such as the two sub-classes observed in the rod-shaped class. This approach will be beneficial especially when heterogeneous populations are present and need to be quantified. In future, such information can be correlated with functional characteristics of produced virus classes and production parameters can accordingly be optimised. The approach thus holds great promise for the production of virus-based therapeutics. We note, however, that the methods presented are generally applicable to other systems and they are not restricted to a particular type of fluorescence microscopy, SRM or not.
Materials and methods

Sample preparation. The purified NDV samples were prepared on cover slips as previously described. Briefly, viruses were adhered on poly-L-lysine-coated Ibidi 8-well dishes, fixed, permeabilised and immunolabelled for the envelope glycoprotein Hemagglutinin-Neuraminidase (HN) with primary antibodies (mouse anti-hemagglutinin-neuraminidase HN, Abcam, UK) followed by secondary labelling (goat anti-mouse labelled with Alexa Fluor 647 for dSTORM, with Alexa Fluor 488 for TIRF-SIM and with ATTO647-N for STED, Abcam, UK).

The LAIV samples were prepared identically but using primary antibodies originating from MedImmune in-house, non-commercially available monoclonals that target the viral glycoprotein Hemagglutinin (HA) present on the exterior of the viral envelope: F16 mouse antibody for B-Victoria, Infa0121 mouse antibody for B-Yamagata and FY1 human antibody for A South Dakota and A Bolivia. The corresponding secondary antibodies were used (donkey anti-mouse DyLight 488 labelled or rabbit anti-human DyLight 488 labelled antibodies, ThermoFisher). All virus samples originated from the monovalent bulk (MVB) and are therefore highly purified, unless indicated in the text, where the direct pool harvest fluid (PHF) was used.

TIRF-SIM, STED and dSTORM imaging. Our custom-built TIRF-SIM system was described previously. We used an Olympus UAPON 100x TIRF NA=1.49 and an Orca Flash 4.0 camera, with a sample pixel size of 64 nm. A total of 9 SIM images were acquired (3 phases, 3 orientations) with a camera exposure time of 200 ms and ~250 µW of 488 nm laser, measured at the back aperture of the objective. The SIM images were obtained using the reconstruction code provided by Dr Lin Shao, providing images with doubled resolution and 32 nm final pixel size using a Wiener filter of 0.01. The STED imaging was performed on our custom-built STED microscope as described previously. The dSTORM imaging was performed on a custom-built single-molecule microscope previously described and with and mercaptoethylamine (MEA) buffer as previously described. The dSTORM image reconstruction was carried out using rapidSTORM 3.

The resolution achieved by the TIRF-SIM microscope was assessed by identifying the edge of the spatial frequency support using the SIMcheck plugin, as shown in Figure 1 – Figure supplement 1. For STED microscopy, the resolution was estimated from cross-sections of 20 nm beads and reporting the full width at half maximum (FWHM). The dSTORM resolution reported here was obtained from the FWHM of the localization precision, estimated by.

Classification. All segmentations, predictors extractions and classifications were performed using MATLAB (Mathworks). A general diagram of the method is shown in Figure 1 – Figure supplement 1. The segmentation was obtained by an initial Otsu binarization and refined by active contour. This allowed a better outline of the particles and efficient separation of particles in close proximity. The particles that were judged too small or too dim to be real particles (based on criteria obtained from the control sample) were excluded from further analysis.

The basic shape features were extracted using the function regionprops. Hu’s image moments were computed from the 71x71 pixels particle image centred on the centre of mass of the particle. The absolute values of the logarithm of the moments were used in the classification. For the features obtained from AlexNet, the individual 71x71 pixels images were resized to 227x227 pixels and used as all three color layers of the RGB images taken by AlexNet. Then, feature extraction was performed using AlexNet as a pretrained network. 4096 features were obtained and data reduction was performed to limit the number of predictors used. For this, the features were averaged within each individual class and the standard deviation of every feature across the classes was computed. The 6 features with the highest standard deviation was selected. For the SURF features, first a bag of visual words was created from the training dataset, this bag was then used to check the presence of visual words in the 71x71 pixels images of individual particles.
Similarly to AlexNet features, we selected only the 6 visual word features with the highest standard deviation across the different classes for classification. This allowed the computation of a total of 24 features for ML.

The classification was performed using a random forest algorithm. The training dataset was made of 370 manually labelled individual particles and was used to train the random forest across 60 epochs. The classification was validated by 10-fold cross validation on the same dataset. The confusion matrix obtained from this cross-validation is shown in Figure 3. At the training stage, the training dataset was augmented 5-fold by transforming the images with image translation and rotation randomly picked between 0 and 1 pixels and between 0 and 360 degrees respectively.

The accuracy of the model was estimated by calculating the fraction of correctly classified particles across all classes.

\[
\text{accuracy} = \frac{\text{Number of particles correctly classified}}{\text{Total number of particles}}
\]

**Predictor scoring.** The predictors were scored by computing the accuracy of the random forest trained on the training dataset but with only subsets of features. Out of the 24 predictors all combinations of 2, 3, 4, 24, 23 and 22 predictors were tested corresponding to a total of 13,227 combinations of predictors. For each combination of predictors, the accuracy obtained was split equally across the different predictors used, producing a “local” accuracy for each feature. This local score was average across all combinations using a specific feature to obtain the global score.

\[
S_i = \frac{1}{N_c^i} \sum_{j=1}^{N_c^i} a_{ij} P_j \frac{1}{n_j}
\]

Where \(S_i\) is the global score of the feature \(i\), \(N_c^i\) is the total number of combinations tested involving feature \(i\), \(a_{ij}\) is a factor reflecting the presence of the feature \(i\) in the combination \(j\). \(a_{ij}\) is equal to 1 if \(i\) is present in \(j\), 0 otherwise. \(P_j\) is the accuracy of the combination \(j\), \(N_c\) is the total number of combination tested and \(n_j\) is the number of features present in the combination \(j\).

**Quantitative analysis.** All quantitative analyses were performed using MATLAB (Mathworks). The length of the filamentous structures were extracted by measuring the geodesic distance along the skeletonized image of the filament. The ELM analysis is freely available and the code was adapted to insert within the workflow of our approach. For ELM analysis, we observed no significant ellipticity in the spherical virus particles and fitted spherical shapes to extract the radius of the particles (Figure 4 – Figure supplement 1).

The equivalent radius \(r\) of the small spherical particles were simply calculated from the area \(A\) of the segmented particle.

\[
r = \sqrt{\frac{A}{\pi}}
\]

The image model for the rod-shaped particles is presented in Figure 1 – Figure supplement 1. Briefly, the backbone of the particle was extracted by image thinning and then dilated by a disk-shaped kernel of radius equal to half of the width of the rod. The length of the rod could be adjusted by shortening the ends of the backbone or by extrapolating it outwards to lengthen it. The interior pixels of the image obtained were removed to leave the outline of the particle shape. This outline was then convolved with a Gaussian kernel in order to take into account the effect of the image resolution (here 90 nm). The intensity, the width and length of the model image were adjusted to minimize the sum of the square difference of intensity \(\chi^2\).
\[ \chi^2 = \sum_{ij} [I_m(i,j) - I_d(i,j)]^2 \]

Where \( i \) and \( j \) refer to the indices in the image, \( I_m(i,j) \) is the image model, and \( I_d(i,j) \) is the original image.

Acknowledgements

RFL and GG were supported by funding from MedImmune Ltd. We thank C. F. van der Walle for critical reading of the manuscript. CFK acknowledges funding from the UK Engineering and Physical Sciences Research Council, EPSRC (grants EP/L015889/1 and EP/H018301/1), the Wellcome Trust (grants 3-3249/Z/16/Z and 089703/Z/09/Z) and the UK Medical Research Council, MRC (grants MR/K015850/1 and MR/K02292X/1), MedImmune and Infinitus (China) Ltd. This project has received funding from the European Union’s Horizon 2020 research and innovation programme under Grant Agreement No. 722380. RFL acknowledges a BBSRC TRDF grant (BB/P027431/1). We would like to thank Hong Jin and Xing Cheng from the Medimmune ID Vaccines group to supply the NDV virus. We would also like to thank Dr Kathryn White and Tracey Davey from the EM Research Services at the Newcastle Medical School for providing examples of TEM images of LAIV samples. Thanks also go to Hong Jin and Dan Pappas for providing TEM images of NDV.
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doi:http://dx.doi.org/10.1016/j.protcy.2014.09.007


Figure 1 – Figure supplement 1: Resolution in SRM. (a) Typical spatial resolution and acquisition times for the imaging of NDV structures highlighting the trade-off between speed and resolution (b) Representative TIRF-SIM image obtained from purified B Victoria LAIV and its corresponding Fourier transform (c). The Fourier transform highlights the resolution ~90 nm. The plot was obtained using the SIMcheck plugin\textsuperscript{33}. (d) Image and cross section of a single secondary antibody labelled with DyLight 488, showing a FWHM of ~90 nm. FFT: Fast Fourier transform.
Table 1: Comparison of the key performance parameters of TIRF-SIM (proposed method) and EM in the context of high throughput imaging of virus structure. The resolution and acquisition time of EM were quoted for a standard TEM imaging (Philips CM 100 Compustage (FEI) Transmission Electron Microscope with an AMT CCD camera). *for a comparable field-of-view.
Figure 2 – Figure supplement 1: Image model for the analysis of the rod-shaped particles. The original image is segmented and thinned to obtain the backbone of the particle. The backbone is up-sampled and interpolated outside the particle. It is then used to compute the model scaffold. For this, each end of the backbone is independently grown or reduced to adjust its length, hence \( L_{\text{RD}} = L_{\text{tot}} - L_1 - L_2 \), where \( L_{\text{tot}} \) is the maximum length of the extended backbone, and \( L_1 \) and \( L_2 \) are the adjusted distances by which the backbone length is adjusted on each end respectively. Then, the image is dilated by a disk-shaped kernel of radius equal to half \( W_{\text{RD}} \). The outline of this image gives the model scaffold. The scaffold is then convolved with a Gaussian kernel representing the effect of image resolution (here 90 nm) and the image is down-sampled again to the original image size. The optimal \( L_{\text{RD}} \) and \( W_{\text{RD}} \) are those that minimize the difference image and the \( \chi^2 \).

Figure 3 – Figure supplement 1: Flowchart describing the machine learning pipeline used here for image classification. A strong emphasis should be put on the choice of predictors and the quality of the manual annotation (training dataset) prior to classification, as this will largely determine the quality of the classification.
Figure 4 – Figure supplement 1: ELM analysis of the large spherical NDV (a) and B-Victoria LAIV (b) viruses. The distribution of diameters were fitted to a Gamma and Gaussian distributions respectively. The mean diameters and standard deviations of the data are shown.

Figure 5 – Figure supplement 1: Structural analysis of B-Victoria LAIV obtained from pool harvested fluid (PHF). (a) TIRF-SIM images. The images acquired here using PHF show an identical image quality as with highly purified samples. (b) Structural analysis of N = 1295 virus particles. Images of individual particles cover a field of view of 1.6 x 1.6 μm.
Supplementary Note 1: Throughput of the method.

The imaging throughput of the method can be assessed in terms of number of particles imaged per second. The field-of-view achievable in our TIRF-SIM system is $\sim32 \mu m \times 32 \mu m$ and a high quality sample preparation can yield a virus particle density of $\sim1$ particle/$\mu m^2$. Therefore, with an acquisition time of 200 ms/SIM raw frame (with a total of 9 frames), we assess that our single frame particle throughput can reach $\sim500$ imaged particles/s. However, the acquisition of two consecutive fields-of-view are affected by imaging dead time as a consequence of stage movement and refocussing. In the study presented here, this step was done manually and took approximately 2-3 s. Therefore, a practical throughput achievable for the imaging is of the order of $\sim220$ particles/s. We note however that both acquisition times and the stage movement time can be easily reduced by increasing illumination power and automation respectively. This makes the 500 particles/s not an unreasonable estimation for the achievable throughput of a further optimised acquisition.

The throughput of the method can also be regarded as the time necessary to perform the complete study from sample preparation to analysis. Table 2 indicates typical times necessary to perform the individual steps of the workflow. This table indicates that a full structural analysis of a particular sample can be obtained within a day.

<table>
<thead>
<tr>
<th>Step</th>
<th>Description</th>
<th>Time</th>
</tr>
</thead>
<tbody>
<tr>
<td>Sample preparation</td>
<td>Plating, permeabilising and immune-labelling of virus particles</td>
<td>2-3h</td>
</tr>
<tr>
<td>Instrument set-up</td>
<td>Quality check of set-up alignment, calibration and sample mounting</td>
<td>30 min</td>
</tr>
<tr>
<td>Imaging</td>
<td>Image acquisition, stage movement and refocus for $\sim50,000$ particles (50 fields-of-view)</td>
<td>30 min</td>
</tr>
<tr>
<td>SIM reconstruction</td>
<td>SR reconstruction of 50 fields-of-view</td>
<td>&lt; 30 min</td>
</tr>
<tr>
<td>Classification on unknown data</td>
<td>Extraction of predictors and classification (for 50 fields-of-view)</td>
<td>1h</td>
</tr>
<tr>
<td>Structural analysis</td>
<td>Extraction of structural parameters for each classes (for 50 fields-of-view)</td>
<td>1h</td>
</tr>
<tr>
<td>Data curation for training dataset</td>
<td>Generating manually labelled particle dataset (performed only once) for $\sim500$ particles</td>
<td>2h</td>
</tr>
<tr>
<td>Generating classification model</td>
<td>Data augmentation, extraction of predictors, training of the model, cross-validation on $\sim500$ particles (performed only once)</td>
<td>5-6 h</td>
</tr>
</tbody>
</table>

Table 2: Estimation of the time necessary to perform individual steps involved in MiLeSIM. Sample preparation was estimated based on standard immuno-labelling protocols. The computational times were assessed on an analysis machine with an i7 processor at 3.5 GHz and 64 GB of RAM.